



DUC-0350-010 REV C

# DEMO9S12XDT512

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DEVELOPMENT BOARD FOR FREESCALE MC9S12XDT512

# CONTENTS

<b>CAUTIONARY NOTES .....</b>	<b>4</b>
<b>TERMINOLOGY.....</b>	<b>4</b>
<b>FEATURES .....</b>	<b>5</b>
<b>REFERENCES .....</b>	<b>6</b>
<b>GETTING STARTED.....</b>	<b>6</b>
<b>OPERATING MODES .....</b>	<b>6</b>
RUN MODE .....	7
DEBUG MODE .....	7
<b>SOFTWARE DEVELOPMENT.....</b>	<b>8</b>
<b>MEMORY MAP .....</b>	<b>8</b>
<b>DEVELOPMENT SUPPORT .....</b>	<b>9</b>
INTEGRATED BDM .....	9
BDM_PORT HEADER.....	9
<b>POWER .....</b>	<b>10</b>
POWER SELECT .....	10
<i>PWR_SEL</i> .....	10
<i>VX_EN</i> .....	11
<b>RESET SWITCH .....</b>	<b>11</b>
<b>LOW VOLTAGE RESET .....</b>	<b>11</b>
<b>TIMING .....</b>	<b>12</b>
<b>COMMUNICATIONS.....</b>	<b>12</b>
RS-232 .....	12
<i>COM CONNECTOR</i> .....	13
LIN COMMUNICATIONS.....	13
<i>LIN_EN</i> .....	13
CAN COMMUNICATIONS.....	14
<b>MODE.....</b>	<b>14</b>
<b>VRH/VRL.....</b>	<b>15</b>
<b>USER I/O.....</b>	<b>15</b>
<i>SWITCHES</i> .....	15
<i>LED'S</i> .....	15
<i>POT</i> .....	16
<i>LIGHT SENSOR</i> .....	16
USER SIGNALS .....	16
USER ENABLE .....	16
<b>MCU I/O PORT.....</b>	<b>17</b>
<b>APPENDIX A.....</b>	<b>19</b>

TOP SILKSCREEN ..... 19

**APPENDIX B.....20**

BILL OF MATERIAL ..... 20

## TABLE OF FIGURES

Figure 1: USB\_SPEED Option Header ..... 9

Figure 2: BDM\_PORT ..... 10

Figure 3: PWR\_SEL Option Header ..... 10

Figure 4. VX\_EN Option Header ..... 11

Figure 5. CLK\_SEL Option Header ..... 12

Figure 6: COM Connector ..... 13

Figure 7: LIN Connector ..... 13

Figure 8. LIN\_EN Option Header ..... 14

Figure 9. CAN\_PORT Connector ..... 14

Figure 10. MODE Option Header ..... 14

Figure 11: MCU I/O PORT – J1..... 17

Figure 12. MCU I/O PORT – J2..... 18

## TABLE OF TABLES

Table 1: Run Mode Setup..... 7

Table 2: BDM Mode Setup ..... 8

Table 3: Memory Map..... 8

Table 4: COM Connections ..... 13

Table 5: ATD Reference Voltage..... 15

Table 6: User I/O ..... 16

Table 7: USER Option Header ..... 17

## Revision History

Date	Rev	Comments
March 24, 2005	A	Initial Release
March 31, 2005	B	Added corrections noted in "Out-of-Box" review. Removed reference to serial cable, Demo program and Troubleshooting section.
May 9, 2005	C	Removed Motorola reference in document

## CAUTIONARY NOTES

- 1) Electrostatic Discharge (ESD) prevention measures should be used when handling this product. ESD damage is not a warranty repair item.
- 2) Axiom Manufacturing does not assume any liability arising out of the application or use of any product or circuit described herein; neither does it convey any license under patent rights or the rights of others.
- 3) EMC Information on the DEMO9S12XDT512 board:
  - a) This product as shipped from the factory with associated power supplies and cables, has been verified to meet with requirements of CE and the FCC as a CLASS A product.
  - b) This product is designed and intended for use as a development platform for hardware or software in an educational or professional laboratory.
  - c) In a domestic environment, this product may cause radio interference in which case the user may be required to take adequate prevention measures.
  - d) Attaching additional wiring to this product or modifying the products operation from the factory default as shipped may effect its performance and cause interference with nearby electronic equipment. If such interference is detected, suitable mitigating measures should be taken.

## TERMINOLOGY

This development module utilizes option select jumpers to configure default board operation. Terminology for application of the option jumpers is as follows:

Jumper – a plastic shunt that connects 2 terminals electrically

Jumper on, in, or installed - jumper is installed such that 2 pins are connected together

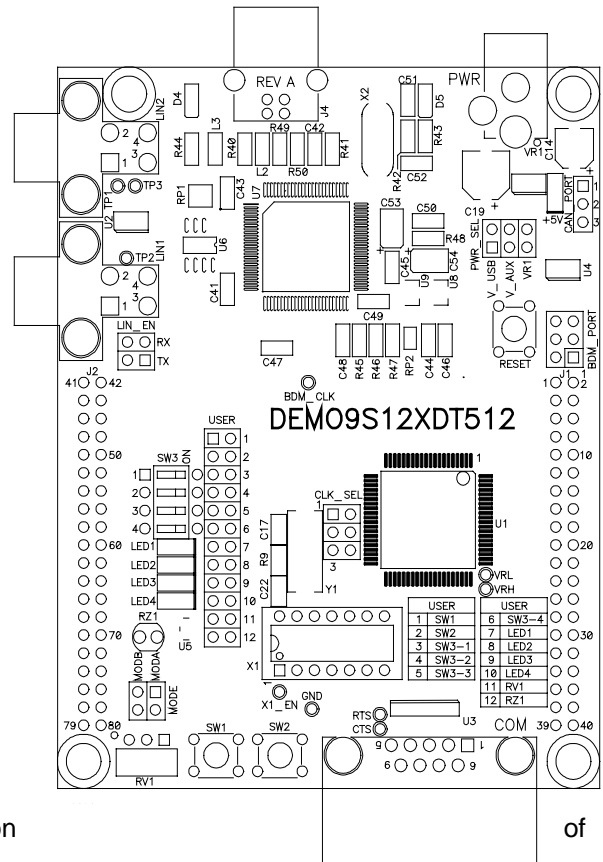
Jumper off, out, or idle - jumper is installed on 1 pin only. It is recommended that jumpers be idled by installing on 1 pin so they will not be lost.

# FEATURES

The DEMO9S12XDT512 is an evaluation or demonstration board for the Freescale MC9S12XDT512 MCU. Development of applications is quick and easy with the integrated USB-Multilink BDM, sample software tools, and examples. A standard BDM debug port is also provided, but not populated, to allow use of an external BDM pod. Two 40-pin connectors allow the demonstration board to be connected to an expanded evaluation environment or to external test equipment.

## Features:

- ◆ MC9S12XDT512 MCU, 80 LQFP
  - ◆ X-GATE Co-Processor
  - ◆ 512 KB Flash EEPROM
  - ◆ 4KB EEPROM
  - ◆ 32 KB SRAM
  - ◆ 59 GPIO lines
  - ◆ Enhanced Capture Timer/PWM
  - ◆ SCI and SPI Communications Ports
  - ◆ Key Wake-up Port
  - ◆ Single Wire BDM Interface
  - ◆ CAN 2.0 A/B Module
  - ◆ Analog to Digital Converter
  - ◆ 80 MHz Bus Operation using internal PLL
- ◆ Integrated USB-Multilink BDM for DEBUG access
- ◆ Optional power from USB bus through USB-Multilink BDM
- ◆ Optional on-board, regulated +5V power supply for stand-alone operation
- ◆ Optional power through MCU I/O connector
- ◆ Power Input Selection
  - ◆ USB Connector
  - ◆ 2.0mm barrel connector
  - ◆ MCU I/O Connector
- ◆ On-Chip Voltage Regulator with low-voltage detect (LVD) and low-voltage interrupt (LVI)
- ◆ 4 MHz crystal oscillator in low-power Pierce configuration default
- ◆ Optional full-power Pierce configuration (requires installation R9)
- ◆ Socket for optional full- or half-can clock oscillator
- ◆ RS-232 serial port w/ DB9 connector
- ◆ 8-Ch, 10-bit, ATD with external trigger capability
- ◆ 16-Ch, 10-bit, ATD with external trigger capability
- ◆ Enhanced Capture Timer with IC, OC, PWM and Pulse Accumulate capabilities
- ◆ User Components Provided
  - ◆ 4 Position DIP Switch
  - ◆ 3 Push Button Switches: 2 User, RESET
  - ◆ 7 LED Indicators: 4 User, 2 USB, +5V
- ◆ Jumpers
  - ◆ Enable/Disable User functions
  - ◆ PWR\_SEL
  - ◆ VX\_EN
  - ◆ LIN\_EN



of

- ◆ CLK\_SEL
- ◆ USB\_SPEED
- ◆ Connectors
  - ◆ Two 40-pin, pass-thru type, MCU I/O Connectors, providing access to most MCU IO signals
  - ◆ 2.0mm barrel connector power input
  - ◆ USB Type-B connector
  - ◆ 6-pin BDM interface connector (not installed)
  - ◆ DB9 COM connector
  - ◆ 2 4-pos LIN connectors
  - ◆ 3-pos CAN connector
- ◆ Supplied with LIN Cable, USB Cable, Documentation (CD), and Manual

**Specifications:**

Module Size 4.0" x 3.1"

Power Input: +6VDC to +18VDC

**NOTE:** LIN functionality supported when powered from PWR connector only

## REFERENCES

Reference documents are provided on the support CD in Acrobat Reader format.

DEMO9S12XDT512_UG_A.pdf	DEMO9S12XDT512 User Guide (this document)
DEMO9S12XDT512QSG.pdf	DEMO9S12XDT512 Quick Start Guide
DEMO9S12XDT512_SCH_D.pdf	DEMO9S12XDT512 Schematic Rev. D
9S12XDP512V2_ZIP.zip	DEMO9S12XDT512 Device User Guide
AN2546.pdf	S12X Load RAM and Execute (LRAE) Program Application Note
AN2615.pdf	HCS12 and S12X Family Compatibility
AN2685.pdf	How to Configure and Use the XGATE on S12X Devices
AN2708.pdf	An Introduction to the External Bus Interface on the HCS12X

## GETTING STARTED

To get started quickly, please refer to the DEMO9S12XDT512 Quick Start Guide. This quick start will show the user how to connect the board to the PC, run a LED test program, install the correct version of CodeWarrior Development Studio, and load an Analog to Digital (ATD) test program using CodeWarrior.

## OPERATING MODES

The DEMO9S12XDT512 board operates in two operating modes: Run Mode, or Debug Mode. Run Mode allows user application operation from Power-On or Reset. Debug Mode supports the development and debug of applications. See the related sections below for quickly starting the board in the desired operation mode.

The board has been preloaded with a demonstration program. The demo program operates in the Run Mode. The +5V LED will light when power is applied to the board.

## RUN MODE

Run mode allows user application to function when power is applied to the board. Use the following settings to configure the DEMO9S12XDT512 board for RUN Mode to get started quickly.

1. Connect auxiliary equipment to board as required by application.
2. Configure the board option jumpers for run mode.

**Table 1: Run Mode Setup**

PWR_SEL	Pin1 – Pin2 (VB)
CLK_SEL	Pin1 – Pin2 (Y1)
VX_EN	Off
USER	As Required
LIN_EN	As Required
USB_SPEED	Pin1 – Pin2 (HIGH)

**NOTE:** See Power section below to configure power input from PWR connector or from J1 connector.

3. Apply power to the board.
4. The programmed application will begin to execute.

## Debug Mode

Debug Mode supports application development and debug. Debug mode is available to the user through the integrated USB-Multilink BDM or the by using an external HCS12 BDM cable. Use of the integrated USB-Multilink BDM requires only a host PC with an available USB port and an A/B type USB cable. A 6-pin BDM interface header (BDM\_PORT) supports the use of an external HCS12 BDM cable. The BDM\_PORT header is not installed in default configuration. The steps below describe using the integrated USB-Multilink BDM.

1. Connect auxiliary equipment to board as required by application.
2. Install and launch P&E PKG12Z tool set, CodeWarrior Development Studio, or other software capable of communicating with the HCS12 MCU.
3. Configure the board option jumpers for DEBUG mode.

**Table 2: BDM Mode Setup**

PWR_SEL	Pin1 – Pin2 (VB)
CLK_SEL	Pin1 – Pin2 (Y1)
VX_EN	Off
USER	As Required
LIN_EN	As Required
USB_SPEED	Pin1 – Pin2 (HIGH)

**NOTE:** Refer to the Development Support section below for details on using an external HCS12 BDM cable.

4. Connect the supplied USB cable between an available USB port on the host PC and the USB connector on the board.
5. Hosting development software will establish DEBUG communication.
6. If the P&E Connection Assistant appears, ensure the following settings

Interface:            USB HCS08/HCS12 MULTILINK – USB PORT  
 Port:                 USB1 : USB-ML-12 REF : DEMO9S12XDT512  
 CPU:                 HC12/HCS12 - Autodetect Device Type

## MEMORY MAP

The table below shows the default memory map for the MC9S12XDP512 immediately out of reset.

**Table 3: Memory Map**

\$0000 - \$07FF	REGISTERS	2 KB	
\$0800 - \$0FFF	EEPROM	4 KB	4 – 1Kb pages between 0x800 – 0xBFF
\$1000 - \$3FFF	RAM	12 KB	5 – 4Kb pages between 0x1000 – 0x1FFF
\$4000 - \$7FFF	FIXED FLASH	16 KB	1K, 2K, 4K, 8K Protected Boot Sector
\$8000 - \$BFFF	FLASH EEPROM PAGE WINDOW	16 KB	32 – 16Kb pages
\$C000 - \$EFFF	FIXED FLASH	16 KB	2K, 4K, 8K, 16K Protected Boot Sector
\$FF00 - \$FFFF	Vectors BDM (if active)	255 bits	

## SOFTWARE DEVELOPMENT

Software development will require the use of an assembler or compiler supporting the HCS12 instruction set and a host PC operating a debug interface. The assembler or compiler must also support the HC(S)12 X-Gate instruction set. CodeWarrior Development Studio and Axiom



IDE for Windows for Debugging and Flash programming are supplied with this board. A demonstration or evaluation copy of a C compiler is also provided.

A powerful source code generation tool called DriveWay™ is also provided on the support CD. This can generate C source code for the HC(S)12 microcontroller peripherals, based on setup. See the DriveWay™ readme.txt file for more information.

## DEVELOPMENT SUPPORT

Application development and debug for the target MC9S12XDT512 is supported through the BDM interface. The BDM interface consists of an integrated USB-Multilink BDM and a 6-pin interface header (BDM\_PORT) to connect a HCS12 BDM cable.

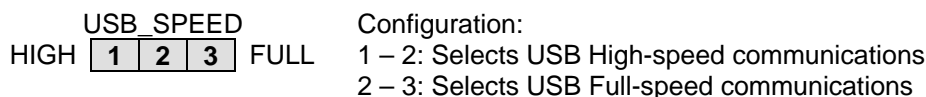
### Integrated BDM

The DEMO9S12XDT512 board features an integrated USB-Multilink BDM from P&E Micro-computer Systems. The integrated USB-Multilink BDM supports application development and debugging via background debug mode. All necessary signals are provided by the integrated USB-Multilink BDM. A USB, type B, connector provides connection from the target board to the host PC.

The integrated USB-Multilink BDM provides +5V power and ground to target board eliminating the need to power the board externally. Power from the USB-Multilink BDM is derived from the USB bus; therefore, total current consumption for the target board, and connected circuitry, must not **exceed 500mA**. This current limit describes the current supplied by the USB cable to the BDM, target board, and any connected circuitry. Excessive current drain will violate the USB specification. Damage to the host PC USB hub or the target board may result.

The communications speed over the USB bus is controlled by the USB\_SPEED header. When shipped from the factory, the DEMO9S12XDT512 is configured for high-speed operation. If the user encounters a communication failure, USB communication speed may be reduced by setting this option jumper to Full.

**Figure 1: USB\_SPEED Option Header**



**CAUTION:** Do not allow total current drain to **exceed 500mA** when powered from the USB-Multilink BDM .

### BDM\_PORT Header

A compatible HCS12 BDM cable can also attach to the 6-pin BDM interface header (BDM\_PORT). This header is not installed in default configuration. The figure below shows the pin-out for the DEBUG header

**Figure 2: BDM\_PORT**

MODC/BKGD	1	2	GND
	3	4	RESET*
	5	6	VDD

See the HC12 Reference Manual for complete DEBUG documentation

**NOTE:** This header is not installed in default configuration.

## POWER

The DEMO9S12XDT512 is designed to be powered through the USB-Multilink BDM during application development. A 2.0mm barrel connector has been applied to support stand-alone operation and to support LIN functionality. The board may also be powered through connector J1. This connection may also be used to supply power from the board to external circuitry.

During application development, the board should be configured to draw power from the USB-Multilink BDM. The barrel connector may be used to support LIN functionality during application development. The barrel connector input is also used to provide power during stand-alone operation.

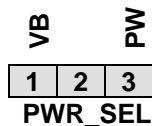
## POWER SELECT

Power may be applied to the board through the integrated USB-Multilink BDM circuitry, a 2.0mm barrel connector, or through connector J1. Power selection is achieved using 2 selection headers: PWR\_SEL option header and the VX\_EN option header.

### *PWR\_SEL*

The PWR\_SEL option header selects power input either from the integrated USB-Multilink BDM circuitry or from the on-board voltage regulator. The figure below details the PWR\_SEL header connections.

**Figure 3: PWR\_SEL Option Header**



**CONFIGURATION**

- 1 – 2: Selects power input from USB-ML12
- 2 – 3: Selects power input from on-board regulator or J1

**NOTE:** Set PWR\_SEL jumper to VB during application development. Use barrel connector input (PWR) to support LIN functionality as needed.

Power from the integrated BDM is drawn from the USB bus and is limited to **500 mA**. This current limit describes the total current supplied over the USB cable to the BDM, target board and any connected circuitry. Current drain in excess of 500 mA will violate the USB specification and may result in damage to the host PC or the target board. At minimum, excessive current

drain will cause the host PC to spontaneously reboot. Power is provided through the integrated BDM to the target board.

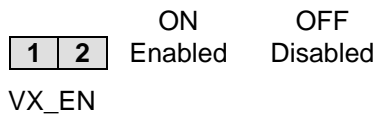
The on-board voltage regulator (VR1) accepts power input through a 2.0mm barrel connector (PWR). Input voltage may range from +6V to +18V. The voltage regulator (VR1) provides a +5V fixed output limited to 250mA. Over-temperature and over-current limit built into the voltage regulator provides protection from excessive stress. Consider the maximum output current limit of VR1 when attempting to power off-board circuitry through connector J1.

### VX\_EN

The VX\_EN option header is a 2-pin jumper that connects/disconnects input J1-1 directly to the target board +5V voltage rail. J1-3 is directly connected to the ground plane. Use of this feature requires a regulated +5V input power source. This power input is decoupled to minimize noise input but is not regulated. Care should be exercised when using this feature; no protection is applied on this input and damage to the target board may result if over-driven. Also, do not attempt to power the target board through this connector while also applying power through the USB-Multilink BDM or the PWR connector; damage to the board may result.

Power may also be sourced to off-board circuitry through the J1 connector. Current output to external circuitry is limited by the current supplied from the USB bus or the on-board regulator. Excessive current drain may damage the target board, the host PC USB hub, or the on-board regulator. The figure below details the VX\_EN header connections.

**Figure 4. VX\_EN Option Header**



**CAUTION:** Do not exceed available current supply from USB-Multilink BDM or on-board regulator, when sourcing power through connector J1 to external circuitry.

## RESET SWITCH

The RESET switch provides a method to apply an asynchronous RESET to the MCU. The RESET switch is connected directly to the RESET\* input on the MCU. Pressing the RESET switch applies a low voltage level to the RESET\* input. A pull-up bias resistor allows normal MCU operation. Shunt capacitance ensures an adequate input pulse width.

## LOW VOLTAGE RESET

The MC9S12XDT512 utilizes an internal Low Voltage Reset (LVR) circuit. The LVR holds the MCU in reset until applied voltage reaches an appropriate level. The LVR also protect against under-voltage conditions. Consult the MC9S12XDT512 reference manual for details LVR operation.

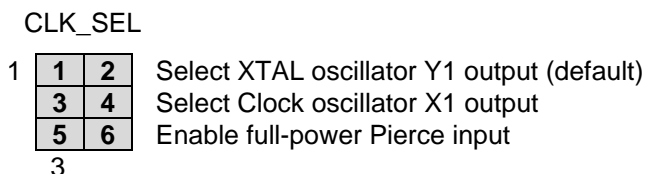
# TIMING

Default timing configuration for the DEMO9S12XDT512 is a low-power, low-noise Pierce oscillator. In this mode, oscillator swing is typically 1V<sub>PP</sub>. The Pierce oscillator input is supplied by a 4 MHz, fundamental frequency, crystal oscillator at location Y1. The crystal oscillator exhibits a frequency tolerance of 30ppm. An optional socket at X1 is also provided to support alternate MCU input frequencies. This socket supports full- and half-size can clock oscillators.

The XCLKS\* signal allows the user to configure the timing input as a full-power Pierce oscillator. Full power Pierce mode requires installing an 0805 size, 1M ohm resistor at location R9. The XCLKS\* jumper should be disabled when using an optional clock oscillator.

The CLK\_SEL option header selects the on-board XTAL oscillator, the optional CLOCK oscillator socket, or configures the MCU to accept a full-power Pierce Oscillator input as timing source for the MCU. The figure below shows settings for CLK\_SEL option header.

**Figure 5. CLK\_SEL Option Header**



**NOTE:** When applying the Clock Oscillator (X1), do not enable XCLKS\*

**NOTE:** Enabling the full-power Pierce oscillator requires installing a 1M ohm resistor at location R9.

# COMMUNICATIONS

The DEMO9S12XDT512 board provides two Enhanced Serial Communications Interface (ESCI) ports. ESCI1 is applied to RS-232 serial communications (COM) on the target board. ESCI2 is applied to LIN communications on the target board. RS-232 communications are supported through a DB9 connector. LIN communications are supported through a pair of 4-pin Molex connectors.

## RS-232

An RS-232 translator provides RS-232 to TTL/CMOS logic level translation on the COM connector. The COM connector is a 9-pin Dsub, right-angle connector. A ferrite bead on shield ground provides conducted immunity protection. Communication signals TXD and RXD are routed from the transceiver to the MCU. Hardware flow control signals RTS and CTS are available on the logic side of U3. These signals are routed to vias located near the transceiver (U3). RTS has been biased properly to support 2-wire RS-232 communications.

Communications signals TXD and RXD also connect to general purpose Port S signals.

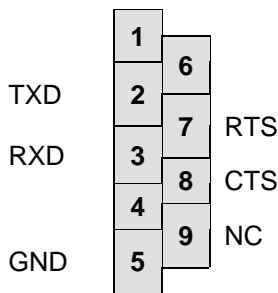
**Table 4: COM Connections**

MCU Port	COM Signal	I/O PORT CONNECTOR
PS1/TXD	TXD OUT	J1-5
PS0/RXD	RXD IN	J1-7

### COM Connector

A standard 9-pin Dsub connector provides external connections for the SCI1 port. The Dsub shell is connected to board ground through a ferrite bead. The ferrite bead provides noise isolation on the RS-232 connection. The figure below details the DB9 connector.

**Figure 6: COM Connector**



Female DB9 connector that interfaces to the MCU internal SCI1 serial port via the RS232 transceiver. It provides simple 2 wire asynchronous serial communications without flow control. Flow control is provided at test points on the board.

**Pins 1, 4, and 6 are connected together.**

## LIN Communications

The DEMO9S12XDT512 applies the MC33661D Local Interconnect Interface (LIN) physical layer (PHY) for use in developing automotive control applications. The MC33661D physical layer interface (PHY) supports LIN bus functionality for input voltages between +6V and +18V. Only power applied to the PWR connector will enable the LIN bus. Two, 4-pin, Molex connectors provide off-board connectivity. The figure below shows the pin-out of the LIN connector looking into the connector.

**Figure 7: LIN Connector**



REF: Mating Connector, Molex P/N, 39-01-2040, Housing  
39-00-0039, Socket

**NOTE:** Board must be powered from the PWR connector with V<sub>IN</sub> between +6V and +18V.

### LIN\_EN

The LIN\_EN option header enables or disables the LIN driver on ESC11.

**Figure 8. LIN\_EN Option Header**

LIN_EN			
4	3	TX	Enable LIN TX
2	1	RX	Enable LIN RX

**NOTE:** Board must be powered from the PWR connector with  $V_{IN}$  between +6V and 18V.

## CAN Communications

The DEMO9S12XDT512 provides a PCA82C250 high-speed CAN physical layer interface (PHY). A 3-pin connector provides connectivity to the off-board CAN bus. The CAN PHY connects to the CAN0 channel on the MCU. The PHY supports data rates up to 1 MBps with edge-rate control to reduce EMI/RFI. The figure below shows the pin-out of the CAN\_PORT connector.

**Figure 9. CAN\_PORT Connector**

1	CAN_H	The CAN PHY connects to the CAN0 channel in the MCU
2	GND	
3	CAN_L	

## MODE

The MODE option header allows the MCU to be configured between the various modes of operation. Refer to the MC9S12XDP512 Device User Guide for further details on operational modes. Although no external memory is available on the DEMO9S12XDT512 board, external bus signals are available at expansion headers J1 and J2. The figure below shows the settings for the MODE option header. MODE selection status is latched at the rising edge of RESET. An internal pull-down biases the MODA and MODB signals during boot. After RESET, the MODA and MODB signals revert to general-purpose I/O functionality.

The MODE option header is not installed in default configuration. Internal bias configures the MCU for single-chip operation out of reset. To configure the MCU for expanded mode operation, install a 2x2 pin header and install shunts as noted below.

**Figure 10. MODE Option Header**

MODE		Installed	Removed
4	3	MODB = 1	MODB = 0
2	1	MODA = 1	MODA = 0

**NOTE:** MODE selection pin status is latched on the rising edge of RESET

**NOTE:** This header is not installed in default configuration

## VRH/VRL

MCU inputs VRH and VRL provide the upper and lower voltage reference for the analog to digital (ATD) converter. By default, VRH is tied to VDD and VRL is tied to ground. Adequate filtering has been added to provide a voltage reference with minimal ripple. Either, or both, references may be isolated to provide alternate ATD input references. A test point via on each signal, labeled VRH, or VRL, provides a convenient attach point.

A 0-ohm configuration resistor allows isolation of each reference voltage. Removing R10 isolates VRH while removing R12 isolates VRL. Install 0805 sized 0-ohm resistors in these locations to restore the board to default configuration.

Care must be exercised when using alternate input references. The associated isolation resistor must be removed before applying an alternate voltage reference or the board may be damaged. The table below summarizes the changes necessary to use alternate VRH and/or VRL.

**Table 5: ATD Reference Voltage**

	Installed (Default)	Removed
R10	VRH = VDD	VRH provided by user
R12	VRL = GND	VRL provided by user

**NOTE:** Damage to the board may result if an alternate reference voltage is attached without first removing the associated configuration resistor.

## USER I/O

User I/O includes 2 push button switches, one 4-position DIP switch, 4 green LEDs, a potentiometer, and a Light Sensor. The sections below provide details on each User I/O. The User option header block enables or disables each User I/O individually.

### *SWITCHES*

The DEMO9S12XDT512 target board provides 2 push button switches and one 4-position DIP switch for user input. Each push button switch is an active low input with a pull-up resistor bias to prevent indeterminate input conditions. Pressing a push-button switch causes a low logic input on the associated input.

Each DIP switch position is an active low input. Use of the DIP switches requires enabling the associated PORTB pull-ups internal to the MCU prevent indeterminate input conditions. Moving a DIP switch position to ON causes a low logic level on the associated input. The figure below shows the USER enable position and associated signal for each user switch.

### *LED'S*

The DEMO9S12XDT512 target board provides 4 green LEDs for output indication. Each LED is an active low output. A series, current-limit resistor prevents excessive diode current. Writing a low logic level to an LED output causes the associated LED to turn on. The figure below shows the USER enable position and associated signal for each user LED.

### POT

A single-turn, 3/8 inch, 5K ohm trimmer potentiometer (POT) has been provided as user, analog input. The part is decoupled to minimize noise during adjustment. The POT connects to analog input PAD05/AN05 on the MCU. The figure below shows the USER enable position and associated signal for the potentiometer.

### LIGHT SENSOR

A 4mm photocell light sensor exhibiting 23K – 33K ohms of output resistance has been provided. Output resistance is inversely related to incident light intensity. A gain stage (U5) amplifies the sensor output before connecting to the MCU. The SENSOR connects to analog input PAD04/AN04 on the MCU. The figure below shows the USER enable position and associated signal for the Light Sensor

## User Signals

The following table shows the connections for each user I/O device.

**Table 6: User I/O**

USER	Ref Des	Signal	Device
1	SW1	PP0/KWP0/PWM0/MISO1	Push Button Switch
2	SW2	PP1/KWP1/PWM1/MOSI1	Push Button Switch
3	SW3-1	PB0	4-pos DIP Switch
4	SW3-2	PB1	4-pos DIP Switch
5	SW3-3	PB2	4-pos DIP Switch
6	SW3-4	PB3	4-pos DIP Switch
7	LED1	PB4	Green LED
8	LED2	PB5	Green LED
9	LED3	PB6	Green LED
10	LED4	PB7	Green LED
11	RV1	PAD05/AN05	Potentiometer
12	RZ1	PAD04/AN04	Light Sensor

## USER ENABLE

The User option header block enables or disables each User I/O device individually. User I/O includes 4 green LEDs, 2 push button switches, one 4-position DIP switch, a Light Sensor, and a potentiometer. Installing a shunt enables the associated option. Removing a shunt disables the associated option. The table below shows the configuration option for each USER I/O.



**Table 7: USER Option Header**

	USER		Shunt		Description
			Installed	Removed	
SW1	1	2	Enable	Disable	Push Button Switch 1
SW2	3	4	Enable	Disable	Push Button Switch 2
SW3-1	5	6	Enable	Disable	DIP Switch Position 1
SW3-2	7	8	Enable	Disable	DIP Switch Position 2
SW3-3	9	10	Enable	Disable	DIP Switch Position 3
SW3-4	11	12	Enable	Disable	DIP Switch Position 4
LED1	13	14	Enable	Disable	LED 1
LED2	15	16	Enable	Disable	LED 2
LED3	17	18	Enable	Disable	LED 3
LED4	19	20	Enable	Disable	LED 4
RV1	21	22	Enable	Disable	Potentiometer
RZ1	23	24	Enable	Disable	Light Sensor

## MCU I/O PORT

The MCU I/O PORT connectors (J1 and J2) provide access to the MC9S12XDT512 I/O signals. The figures below show the pin-out for each MCU I/O connector.

**Figure 11: MCU I/O PORT – J1**

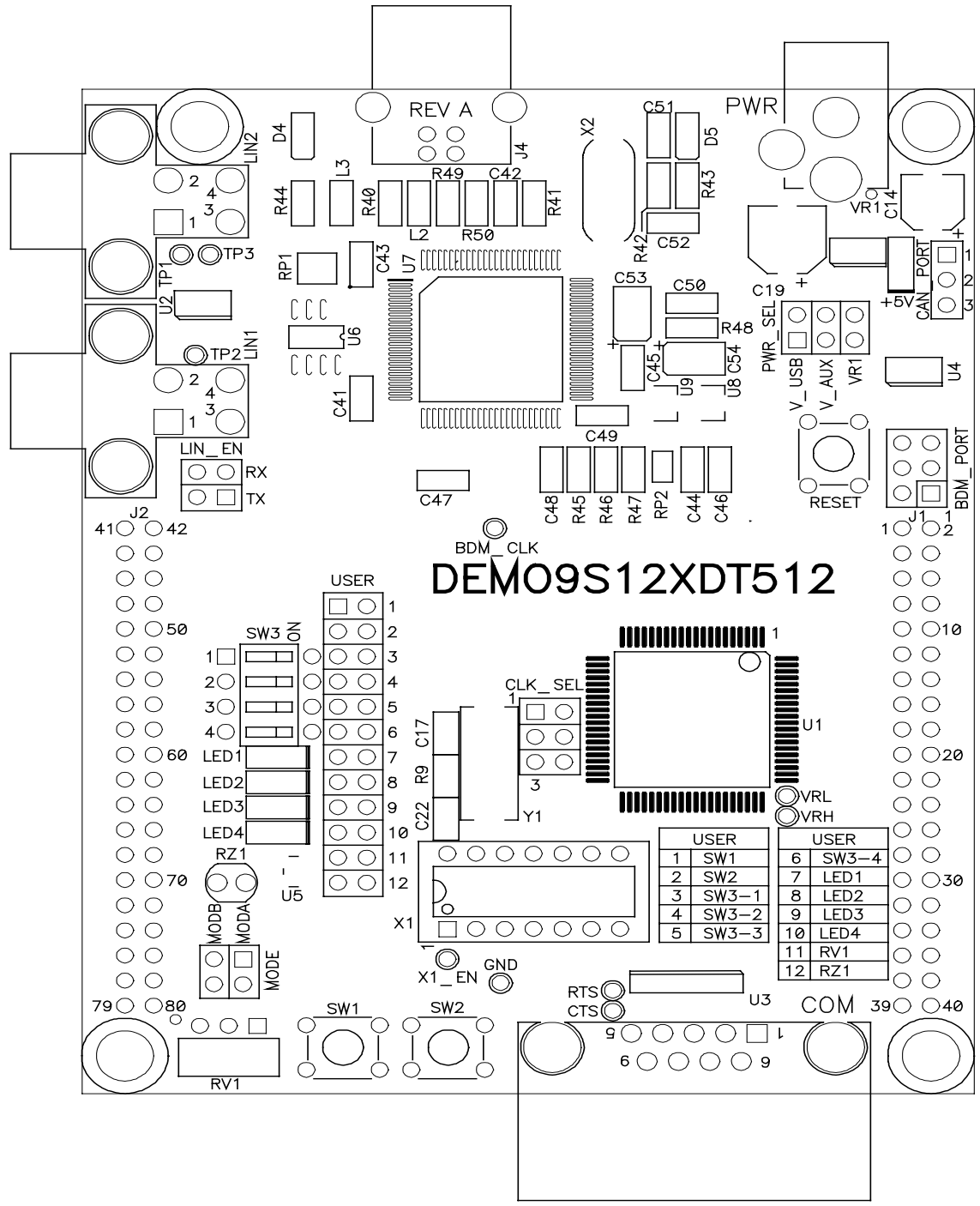
		J1		
VDD	1	2	IRQ/PE1	
VSS	3	4	RESET*	
PS1/TXD0	5	6	MODC/BKGD	
PS0/RXD0	7	8	PP7/KWP7/PWM7/SCK2	
PP0/KWP0/PWM0/MISO1	9	10	PAD07/AN07	
PP1/KWP1/PWM1/MOSI1	11	12	PAD06/AN06	
PT0/I0C0	13	14	PAD05/AN05	
PT1/I0C1	15	16	PAD04/AN04	
PM4/RXCAN2/RXCAN0/RXCAN4/MOSI0	17	18	PAD03/AN03	
PM2/RXCAN1/RXCAN0/MISO0	19	20	PAD02/AN02	
PM5/TXCAN2/TXCAN0/TXCAN4/SCK0	21	22	PAD01/AN01	
PM3/TXCAN1/TXCAN0/SS0	23	24	PAD00/AN00	
PA7	25	26	PJ6/KWJ6/RXCAN4/SDA0	
PA6	27	28	PJ7/KWJ7/TXCAN4/SCL0	
PA5	29	30	PP2/KWP2/PWM2/SCK1	
PA4	31	32	PP3/KWP3/PWM3/SS1	
PA3	33	34	PP4/KWP4/PWM4/MISO2	
PA2	35	36	PP5/KWP5/PWM5/MOSI2	
PA1	37	38	PS2/RXD1	
PA0	39	40	PS3/TXD1	

**Figure 12. MCU I/O PORT – J2**

		<b>J2</b>		
PB0	<b>41</b>	<b>42</b>		PM0/RXCAN0/RXB
PB1	<b>43</b>	<b>44</b>		PM1/TXCAN0/TXB
PB2	<b>45</b>	<b>46</b>		IOC2/PT2
PB3	<b>47</b>	<b>48</b>		IOC3/PT3
PB4	<b>49</b>	<b>50</b>		
PB5	<b>51</b>	<b>52</b>		
PB6	<b>53</b>	<b>54</b>		
PB7	<b>55</b>	<b>56</b>		
IOC4/PT4	<b>57</b>	<b>58</b>		
IOC5/PT5	<b>59</b>	<b>60</b>		
IOC6/PT6	<b>61</b>	<b>62</b>		
IOC7/PT7	<b>63</b>	<b>64</b>		
PE7/XCLKS	<b>65</b>	<b>66</b>		
PE6/MODB	<b>67</b>	<b>68</b>		
PE5/MODA	<b>69</b>	<b>70</b>		
PE4/ECLK	<b>71</b>	<b>72</b>		
PE3	<b>73</b>	<b>74</b>		
PE2	<b>75</b>	<b>76</b>		
	<b>77</b>	<b>78</b>		
PE0/XIRQ*	<b>79</b>	<b>80</b>		

# APPENDIX A

## Top Silkscreen



# APPENDIX B

## BILL OF MATERIAL

Item	Qty	Title	Ref	Mfr	Mfr-P/N
1	3	Cap, Tant, 10uF, 10V, SMB	C19, C25, C40	Avx	TAJB106K010R
2	1	Cap, Elect, 100uF, 16V, Alum, SMD	C21	Nichicon	UWX1C101MCL1GB
3	1	Cap, Elec, 10uF, 35V, Alum, SMC	C14	Nichicon	UWX1V100MCL1GB
4	3	Cap, Cer, .22uF, 10V, X7R, 20% 0805	C27, C30, C31	Avx	08053C224MAT2A
5	2	Cap, Cer, 20pF, 50V, NPO/COG, 5%, 0805	C17, C22		
6	1	Cap, Cer, 470pF, X7R, 10%, 0805	C26		
7	1	Cap, Cer, 4700 pF, X7R, 10%, 0805	C32		
8	15	Cap, Cer, .1uF, 50V, 0805	C1, C9, C10, C12, C15, C16, C18, C20, C23, C28, C34, C35, C36, C38, C55	Meritek	MA080525U104M500
9	7	Cap, Cer, .01uF, 50V, 0805	C4, C8, C11, C24, C29, C37, C39		
10	5	Cap, Cer, 1uF, 16V, 0805	C2, C3, C5, C6, C7		
11	3	Res, Car, 4.7K ohm, 1%, 0805	R11, R29, R30		
12	5	Res, Car 680 ohm, 5%, 0805	R5, R23, R24, R26, R28		
13	0	Res, Car, 1M ohm, 5%, 0805	R9	<b>Do Not Install</b>	
14	1	Res, Car, 33K ohm, 5%, 0805	R1		
15	2	Res, Car, 0 ohm, 5%, 0805	R10, R12		
16	5	Res, Car, 10K ohm, 5%, 0805	R2, R4, R21, R22, R34		
17	6	Res, Car, 1K ohm, 5%, 0805	R3, R6, R13, R14, R19, R20		
18	1	Res, Car, 20K ohm, 5%, 0805	R33		
19	2	Res, Car, 47K ohm, 5%, 0805	R35, R39		
20	1	Res, Car, 3.3K ohm, 5%, 0805	R38		
21	1	Res, Car, 100 ohm, 5%, 0805	R25		
22	1	Res, Car, 120 ohm, 5%, 0805	R27		
23	1	Res, Pot, 5K ohm, 9mm vert.	RV1	Bourns	3352W-1-502
24	2	Diode, Rect, S1A, 1A, 50V, DO214AC	D1, D2	Vishay	S1A
25	1	Diode, Schottky, 30V, 200mA, BAT54C, Com. Cathode, SOT23	D3	General Semi	
26	5	LED, Green, w/reflector, 1206, SMT	LED1, LED2, LED3, LED4, +5V	Rohm	SML-010MTT86
27	1	Ind, 10uH, 10%, 1210	L1	Vishay	IMC1210SY100K

28	1	Ind, Ferrite, EMI, 330 ohm @ 100 MHz, 1.5A, 0805	FB1	Mouser	81-BLM21P331SG
29	1	IC, MCU, 9S12XDT512, 80LQFP	U1	Freescale	MC9S12XDT512CFU
30	1	IC, LIN XCVR, MC33661D,SOIC8	U2	Freescale	MC33661D
31	1	IC, CAN XCVR, High Spd, PCA82C250, 8SOIC	U4	Phillips	PCA82C250T
32	1	IC, Dual RS232 XCVR, 3.3V, ESD, 16SOIC	U3	Intersil	ICL3232CBN
33	1	IC, OPAMP, LMV321, Single, SOT23-5	U5	Fairchild	LMV321AS5X
34	1	VReg, LDO, 5.0V, 250mA, 8 SOIC	VR1	STM	L4931CD50
35	1	XTAL, 4.000MHz, 20pf, HC49/US, SMT	Y1	ECS	ECS-40-20-5P-TR
36	1	Sensor, Photocell, 30K -1M	RZ1	Photonic	PDV-P9003
37	1	Sw, DIP, 4 pos, SPST, Thru	SW3	Alcoswitch	3-435640-5
38	3	Sw, PB, Mom, 5mm Sq, Thru	SW1, SW2, RESET	E-Switch	EG1827
39	2	Conn, 2x20 Socket Hdr, Pass Thru, .1" ctr, Bottom Entry, SMT	J1, J2	Townes	F211-220MGF-A
40		Cross to 38 above		Methode	9200-420-501
41	2	Conn, Mini-fit 4 position, RA, thru	LIN1, LIN2	Molex	39-29-5043
42	1	Conn, 1x2, pin header, .1" ctr, thru	VX_EN		
43	2	Conn, 1x3, pin header, .1" ctr, thru	CAN_PORT, PWR_SEL		
44	1	Conn, 2x2 pin header, .1" ctr, thru	LIN_EN		
45	0	Conn, 2x2 pin header, .1" ctr, thru	MODE	<b>Do Not Install</b>	
46	1	Conn, 2x3, pin header, .1"ctr, thru	CKL_SEL		
47	0	Conn, 2x3, pin header, .1"ctr, thru	BDM_PORT	<b>Do Not Install</b>	
48	1	Conn, 2x12, pin header, .1"ctr, thru	USER		
49	1	Conn, Dsub, 9P, F, RA, PCB Mount	COM		
50	1	Conn, Socket, IC, 14P Machine DIP, .3", Thru	X1		
51	1	Conn, 2mm, Pwr Jack, Barrel, Thru, RA	PWR		
52	1	Hdw, Pin Hdr, 1x1, thru	GND		
53	17	Hdw, Shunt, .1" ctr	USER(12), CLK_SEL(1), PWR_SEL(1), LIN_EN(2), USB_SPEED(1)		
54	1	PCB, DEMO9S12XDP512, 3.0"x4.0", 2 layer			
55		<b>USB-BDM IP BLOCK (5V)</b>			
56	3	Cap, Tant, 4.7uF, 16V, A Case	C46, C53, C54	Panasonic	ECS-T1CY475R
57	4	Cap, Cer, .1uF, 25V, 10%, X7R, 0805	C41, C42, C47, C49	Yageo	08052R104K8B20D
58	0	Cap, Cer, .1uF, 25V, 10%, X7R, 0805	C45, C44, C48	<b>Do Not Install</b>	Yageo 08052R104K8B20D
59	2	Cap, Cer, 22pF, 50V, 5%, NPO, 0805	C51, C52	Kemet	C0805C220J5GACTU
60	2	Cap, Cer, .01uF, 50V, X7R, 0805	C43, C50	Kemet	C0805C103K5RACTU
61	1	Res, Ntwk, 1K ohm, Iso, 8P4R, SMD	RP1	CTS	742C083102J
62	1	Res, Ntwk, 4.7K ohm, Iso, 4P2R, SMD	RP2	CTS	742C04342JCT

63	1	Res, 0 ohm, 5%, 0805	R48		
64	2	Res, 33 ohm, 1%, 0805	R49, R50		
65	2	Res, 47 ohm, 5%, 0805	R46, R47		
66	2	Res, 680 ohm, 5%, 0805	R43, R44		
67	1	Res, 510 ohm, 5%, 0805	R40		
68	1	Res, 1K ohm, 5%, 0805	R45		
69	1	Res, 1.5K ohm, 5%, 0805	R41		
70	1	Res, 1M ohm, 5%, 1/4W, 0805	R42		
71	1	Res, 10K ohm, 5%, 0805	R51		
72	2	Ind, Ferrite , EMI, 1.5A, 26 ohm, 1206, SMD	L2, L3	Steward	MI1206K260R-00
73	0	Trans, MOSFET, N-Ch, 20V, 750 mA, SOT-23	U9	<b>Do Not Install</b>	On Semi MGSF1N02ELT1
74	1	Trans, MOSFET, P-Ch, -20V, -3.7A, SOT-23	U8	IR	IRLML6402TR
75	1	LED, Green, w/reflector, 1206, SMT	D4	Rohm	SML-010MTT86
76	1	LED, Yellow, w/reflector, 1206, SMT	D5	Rohm	SML-010YTT86
77	1	IC, LV Reset, 5V, 8SOIC	U6	On Semi	MC34164D-5R2
78	1	IC, MCU, MC9S12UF32PU, 100TQFP	U7	Freescale	MC9S12UF32PU,
79	1	IC, Analog Sw, Bilateral, Dual, SSOP	U10	TI	SN74LVC66DCT
80	1	XTAL, 12.000 MHz, SMT, 18PF	X2	Citizen	HCM49-12.000MABJT
81	1	Conn, 1x3, pin hdr, .1" ctr, thru	J5 (USB_SPEED)		
82	1	Conn, Sckt, USB, Type B, Horiz, thru	J4	Keystone	924K
83		<b>ASSEMBLY</b>			
84	1	Assy, Cable, LIN, 24in, 4pos - 4pos, Latch		Axiom	CBL-LIN001
85	1	Assy, Cable, USB, A-B, 1.8 m, Black		Kobiconn	172-1024
86	1	Freescale box			
87	1	Foam Set			
88	1	Assmby Cost			